

# PA10 Series

## Multifunctional sensor controller

### ■ Features

- 12 kinds of various operation modes selected by DIP S/W
- High speed input response
- Flip-flop function is built in for level control
- Multifunction type with Timer function
- DIN rail mounting and mountable without the rail
- Wide range of power supply (100–240VAC 50/60Hz)

**⚠ Please read "Caution for your safety" in operation manual before using.**



### ■ Ordering information

PA 10 — U □

	NPN input
P	PNP input
U	High function controller
V	Controller
W	2 channel controller
10	Multi-function
PA	Power Amplifier

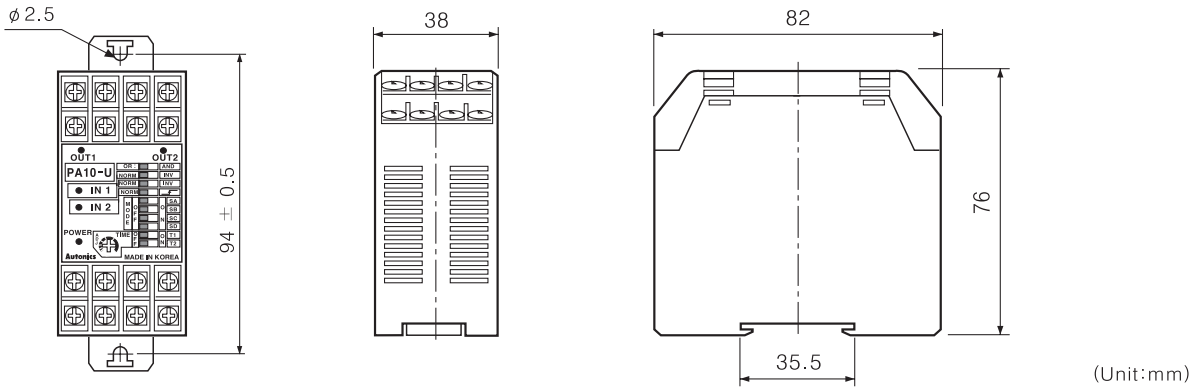
### ■ Specifications

Model	PA10-U	PA10-V	PA10-VP	PA10-W	PA10-WP
Power supply	100–240VAC 50/60Hz				
Allowable operation voltage	90~110% of rated voltage				
Power consumption	100VAC 50/60Hz : Approx. 7VA (Condotion:12VDC/200mA resistive load), 240VAC 50/60Hz : Approx. 10VA				
Power for external sensor	12VDC ±10% max. 200mA				
Input(IN1)(IN2)	Selectable NORM/INV. Selectable OR/AND operation for IN1, IN2 input. Selection function for IN2 derivative action.	Selectable NORM/INV. Operation for IN1, IN2 AND.		Selectable NORM/INV. Selection function for IN1, IN2 individual operation.	
	<b>NPN input type</b>	<b>NPN input type</b>	<b>PNP input type</b>	<b>NPN input type</b>	<b>PNP input type</b>
Input type	<b>●PA10-U</b> [No-voltage input] Impedance at short-circuit:Max. 680Ω, Residual voltage at short-circuit:Max. 0.8V, Impedance at open:Min. 100kΩ <b>●PA10-V/PA10-W</b> [No-voltage input] Impedance at short-circuit:Max. 300Ω, Residual voltage at short-circuit:Max. 2V, Impedance at open:Min. 100kΩ <b>●PA10-VP/PA10-WP</b> [Voltage input] Input impedance:5.6kΩ, "H" level voltage:5–30VDC, "L" level voltage:0–2VDC				
Output	Contact output	OUT : 250VAC 3A(resistive load)		OUT1, OUT2 : 250VAC 3A(resistive load)	
	Solid-state output	O • C OUT1/O • C OUT2 : NPN open collector output Max. 30VDC 200mA	O • C OUT : NPN open collector output max. 30VDC 200mA		—————
Response time	Relay contact : Approx. 10ms, Transistor output : Max. 0.5μs (When it is encoder mode)				
Timer function	<ul style="list-style-type: none"> <li>• ON-Delay</li> <li>• OFF-Delay</li> <li>• Flicker</li> <li>• Flicker One-shot</li> <li>• High-Speed Detection</li> <li>• Low-Speed Detection</li> <li>• One-Shot Delay</li> </ul> Selectable(0.01~0.1/0.1~1/1~10/10~100 sec)	Have	—————		
	<ul style="list-style-type: none"> <li>• NORMAL</li> <li>• FLIP-FLOP</li> <li>• ENCODER(Mode 9~11)□</li> </ul>	None	—————		
Relay life cycle	Mechanical	Min. 10,000,000 times			
	Electrical	Min.100,000 times(250VAC 3A resistive load)			
Dielectric strength	2000VAC 50/60Hz for 1 minute				
Insulation resistance	Min. 100MΩ (at 500VDC)				
Ambient temperature	-10 ~ 55°C (at non-freezing status)				
Storage temperature	-25 ~ 60°C (at non-freezing status) □				
Ambient humidity	35 ~ 85%RH				
Unit weight	Approx. 150g			Approx. 160g	

※If the load is connected over 200mA at the sensor output, it may cause malfunction.

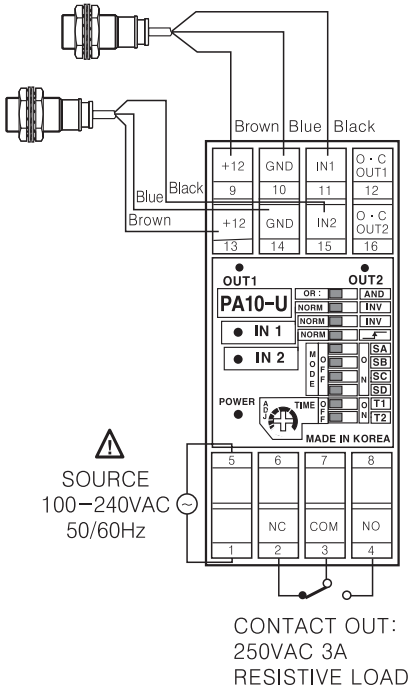
# Sensor Controller

## Dimensions

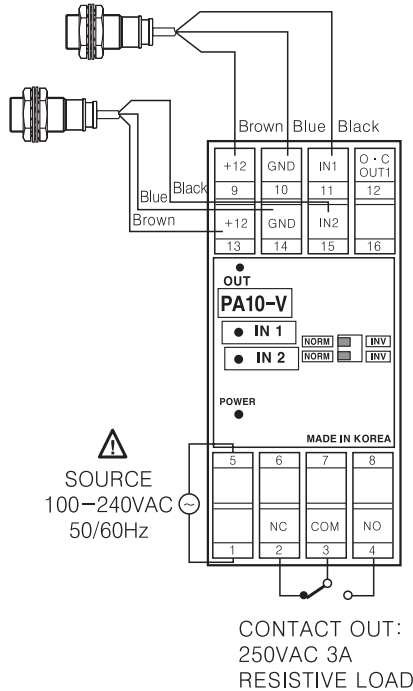


## Connections

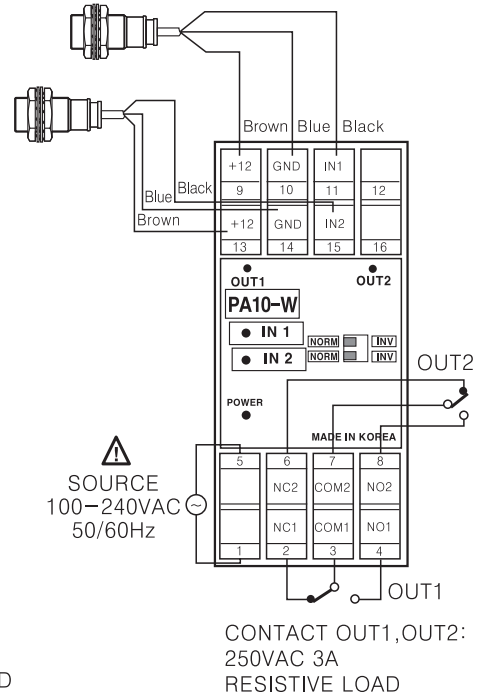
### ●PA10-U



### ●PA10-V/PA10-VP

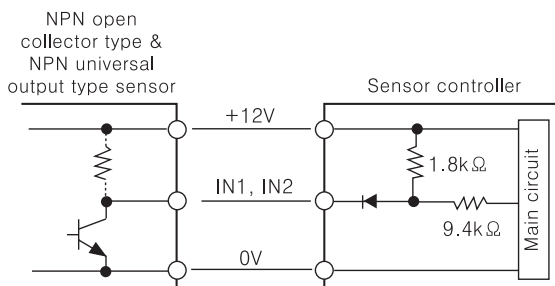


### ●PA10-W/PA10-WP

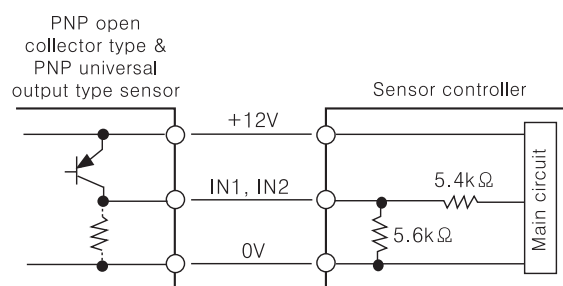


## Input connctions

### ●PA10-U / PA10-V / PA10-W



### ●PA10-VP / PA10-WP



(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

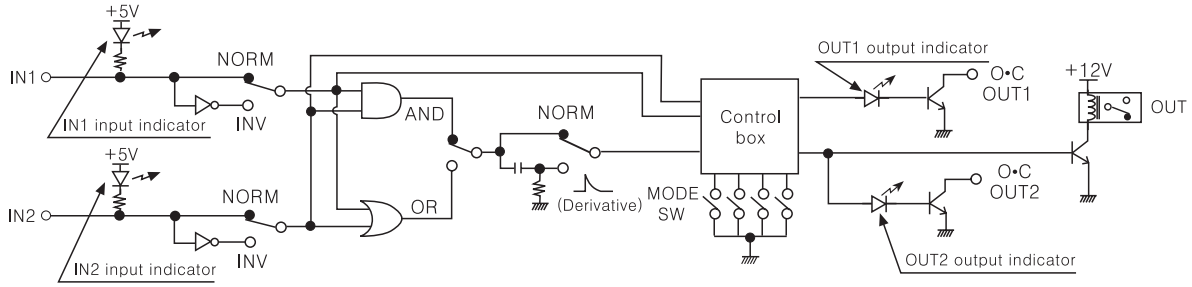
(O) Graphic panel

(P) Production stoppage models & replacement

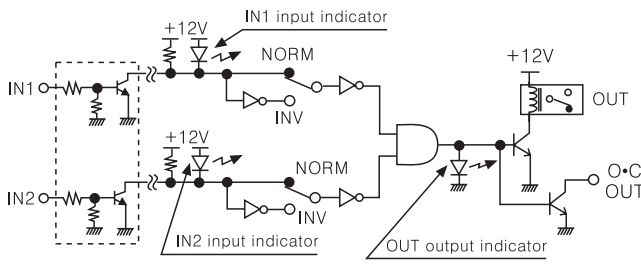
# PA10 Series

## Function diagram

### PA10-U

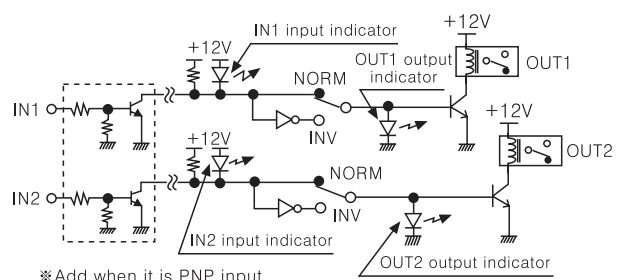


### PA10-V PA10-VP



※Add when it is PNP input

### PA10-W PA10-WP



※Add when it is PNP input

## Front panel identification

### PA10-U

#### 1 Power indicator :

LED is turned on when AC power applied

#### 2 Output indicator 1 : Indication of output signal

#### 3 Output indicator 2 : Indication of output signal

#### 4 Sensor input indicator :

Indication of sensor input signal  
(LED is turned on when sensor input is Low)

#### 5 AND/OR selection switch :

Select "AND" or "OR" for IN1, IN2 Input

#### 6 Selection switch of sensor input signal :

**NORM**  **INV** (Reverse function of input signal)

●NORM : LED is turned on when input signal is low. (  $\bar{A}$  )

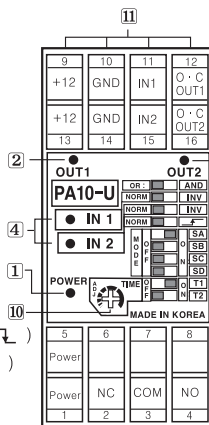
●INV : LED is turned on when input signal is high. (  $A$  )

#### 7 Derivative action selection of IN2 input signal (OR/AND selection switch : AND):

**NORM**   (When input signal is high (  $A$  ), it is effective signal)

●NORM: IN2 input signal is operating as reverse turn function

● : Derivative action of IN2 input signal. (\*Refer to H-7, application of derivative operation.)



#### 8 Selection switch for operation mode :

See <Operation mode> in next page.

#### 9 Selection switch of time range and max. input frequency :

It is the switch to select time range (1~7 mode) or allowable input frequency(9~11 mode).



●Time range : Approx. 0.01 ~ 0.1sec.

Max. input frequency : 100kHz

●Time range : Approx. 0.1 ~ 1sec.

Max. input frequency : 10kHz

●Time range : Approx. 0.1 ~ 10sec.

Max. input frequency : 1kHz

●Time range : Approx. 10 ~ 100sec.

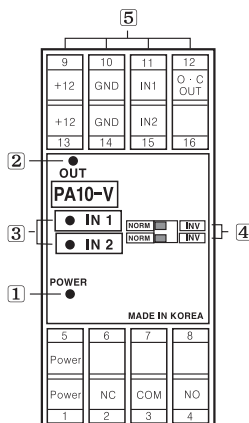
Max. input frequency : 100Hz

#### 10 Timer volume :

Adjust time as same as the range of No. 9 function.

#### 11 Terminal block

### PA10-V/PA10-VP



#### 1 Power indicator :

LED is turned on when AC power applied

#### 2 Output indicator :

Indication of output signal

#### 3 Sensor input indicator :

●PA10-V : Indication of sensor input signal(LED turns on when sensor input is Low)  
●PA10-VP : Indication of sensor input signal(LED turns on when sensor input is High)

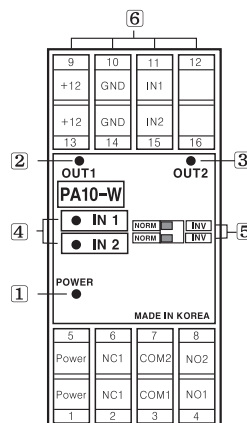
#### 4 Selection switch of sensor input signal

●NORM : LED is turned on when input signal is low.  
●INV : LED is turned on when input signal is high.

#### 5 Terminal block

※When IN1, IN2 input signal is AND, OUT will work.

### PA10-W/PA10-WP



#### 1 Power indicator :

LED is turned on when AC power applied

#### 2 Output indicator :

Indication of output signal

#### 3 Sensor input indicator :

●PA10-W : Indication of sensor input signal(LED is turned on when sensor input is Low)  
●PA10-WP : Indication of sensor input signal(LED is turned on when sensor input is High)

#### 4 Selection switch of sensor input signal

●NORM : LED is turned on when input signal is low.  
●INV : LED is turned on when input signal is high.

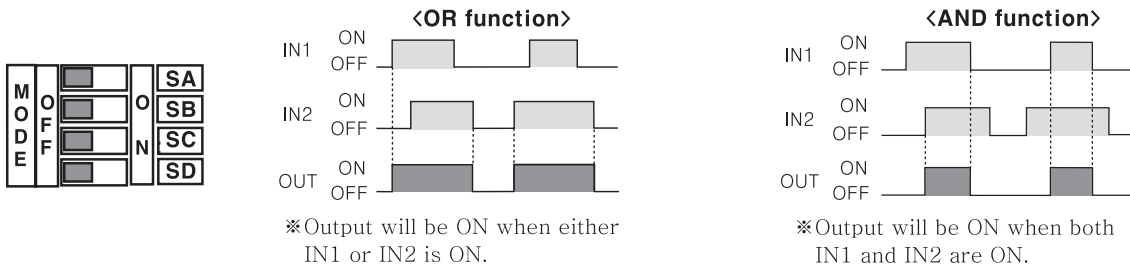
#### 5 Terminal block

※Selectable NORM/INV.  
Selection function for IN1, IN2 individual operation.

## ■ Operation mode(PA10-U)

### ● MODE 0 NORMAL MODE

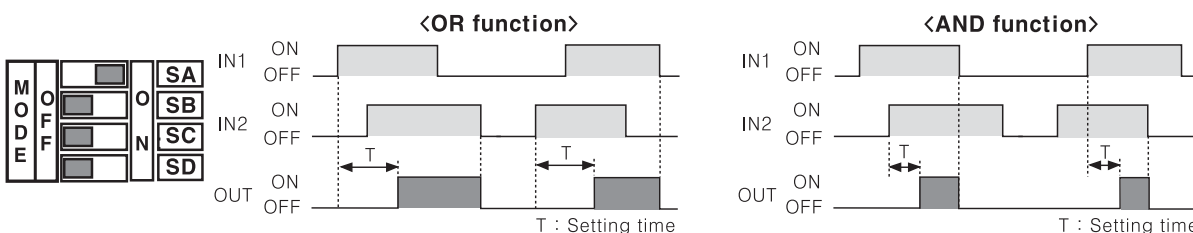
OUT operates according to input signal, regardless of Timer.



### ● MODE 1 ON-DELAY MODE

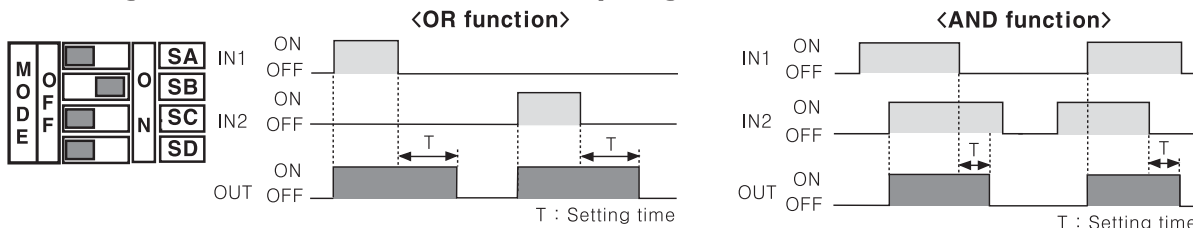
OUT will be ON after delayed as setting time according to one of IN1 and IN2 is ON.

When IN1 and IN2 are OFF, OUT will be OFF. (This is when input logic is OR.)



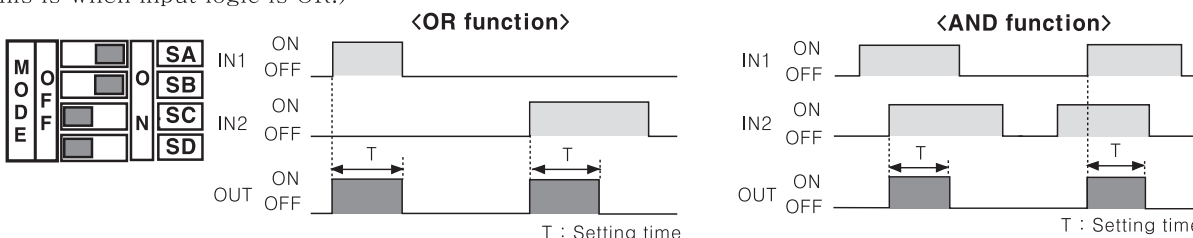
### ● MODE 2 OFF-DELAY MODE :

OUT will be ON at the same time when IN1 or IN2 is ON then OUT will be OFF after delayed as setting time according to IN1 or IN2 is OFF. (This is when input logic is OR.)



### ● MODE 3 ONE-SHOT DELAY MODE

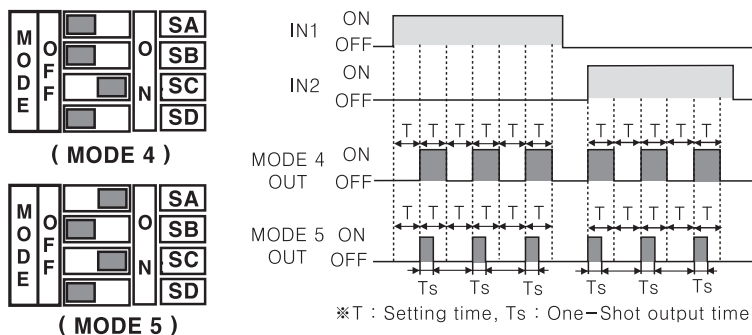
OUT will be ON at the same time with IN1 or IN2 is ON then OUT will be OFF after delayed as setting time. (This is when input logic is OR.)



### ● MODE 4, 5 FLICKER MODE / FLICKER ONE-SHOT MODE

OUT will be ON after delayed as setting time for IN1 input then it is flashing and OUT will be flashing after setting time from ON. But, in case of One-shot Mode, output time(Ts) will be selected by  NORM  S/W.

(  : Ts = Approx. 10ms,  NORM : Ts = Approx. 100ms)



Note) ON/OFF ratio of Flicker output is 1:1.

Note) In case of Flicker Mode, it is not different between  OR  AND and  NORM  S/W.

Note) In case of One-Shot Mode, it is not different between  OR  AND S/W.

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/Speed/Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

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(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

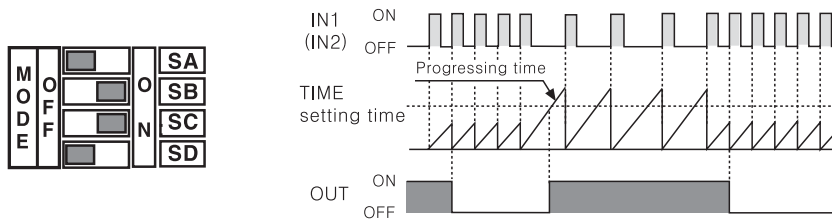
(P) Production stoppage models & replacement

# PA10 Series

## ■ Operation mode(PA10-U)

### ● MODE 6 LOW-SPEED DETECTION MODE

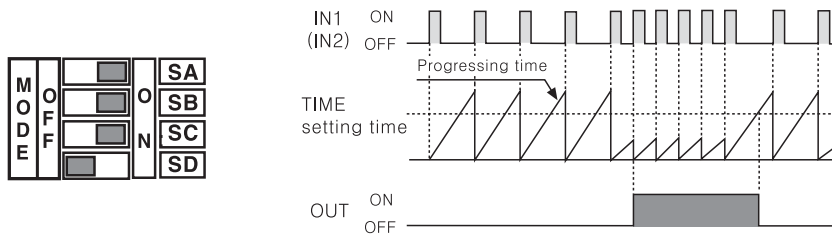
OUT will be ON when input signal(IN1) is longer than setting time by comparing it to the setting time by one cycle.



Note) Above is when input logic is OR and it will be the same by using IN2 input signal terminal instead of IN1.  
 Note) When use MODE 6 as above, be sure that OUT will be work at the same time with power supply.

### ● MODE 7 HIGH-SPEED DETECTION MODE

OUT will be ON when input signal(IN1) is shorter than setting time by comparing it to the setting time by one cycle.



Note) Above is when input logic is OR and it will be the same by using IN2 input signal terminal instead of IN1.

## ◎ TIME S/W function(MODE 1 ~ MODE 7)

Set the setting time by TIME S/W(T1, T2) and front TIME VOLUME(ADJ).

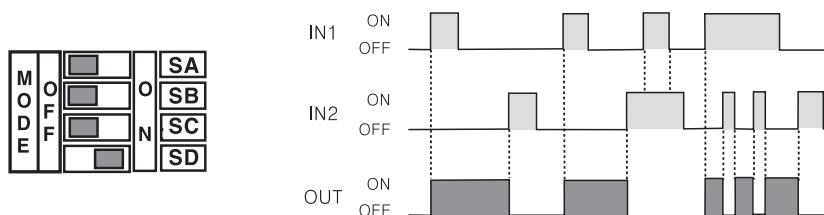
Mode Item	MODE 1 ~ MODE 7	MODE 6 ~ MODE 7
	Setting time range	Input frequency range (※rpm)
	0.01 ~ 0.1sec	100 ~ 10Hz (6,000 ~ 600rpm)
	0.1 ~ 1sec	10 ~ 1Hz (600 ~ 60rpm)
	1 ~ 10sec	1 ~ 0.1Hz (60 ~ 6rpm)
	10 ~ 100sec	0.1 ~ 0.01Hz (6 ~ 0.6rpm)

※Range of operating rpm is 1 pulse per 1 revolution.

※When the pulse is increasing per 1 revolution, range of operating rpm is decreasing.

### ● MODE 8 Flip-Flop MODE [ OUT LATCH operation ]

When IN1 signal is input then the Flip-Flop output will be ON(SET). When the IN2 signal is input, Flip-Flop Signal will be OFF(RESET).



Note) IN2 will be prior to all input signal.

Note) Both  OR  AND and  NORM  S/W are allowed to use.

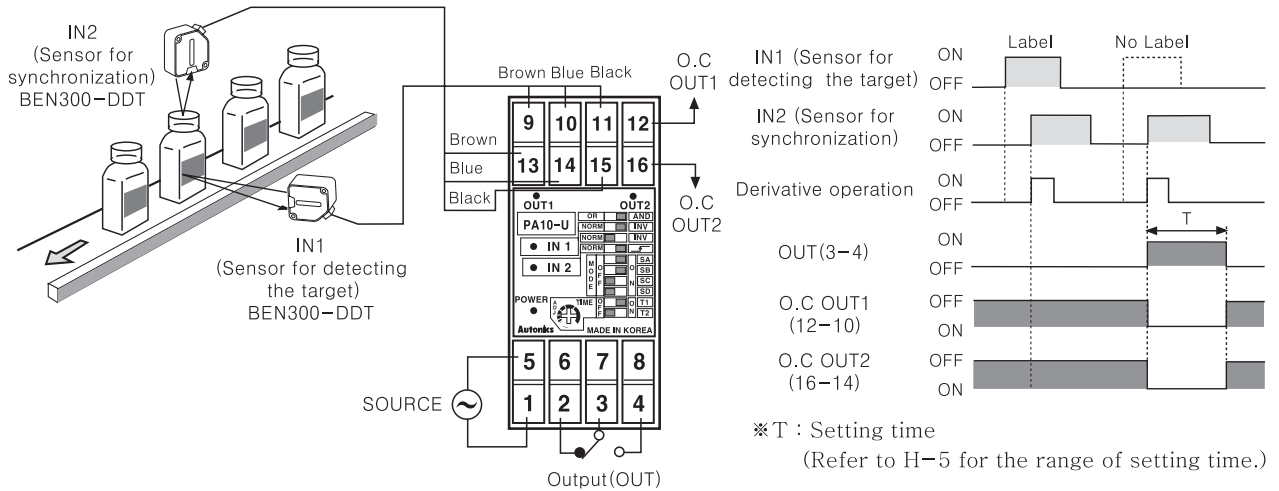
Note) There is no Timer function in Flip-Flop Mode, therefore use this unit with Time S/W(T1, T2) are OFF.



# PA10 Series

## Application of derivative operation

### Detect label of glass bottle



### Operation

When IN2 is ON after IN1 is ON, OUT will not operate. But if there is no label on bottle, OUT will operate with IN2 is ON only. OUT will be returned after setting time.

Note) Please install the sensor (IN1) to be operated first.

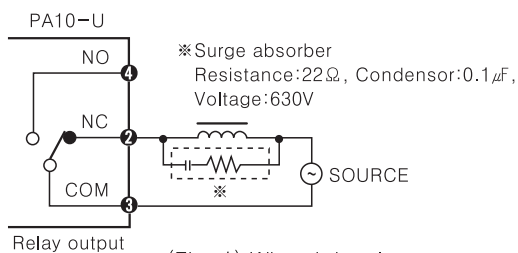
## Proper usage

### Load connections

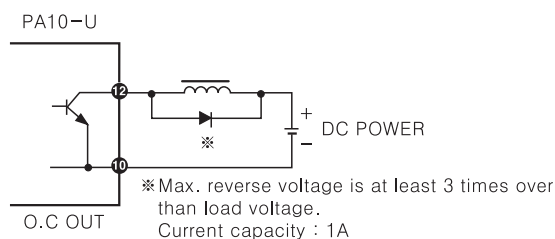
It is important to protect from surge or noise by installing a surge absorber across inductive loads (Motor, Solenoid, etc).

In case the load is a DC relay, please install a diode across relay as shown below.

(Be sure to observe proper polarity)



(Fig. 1) When it is relay output



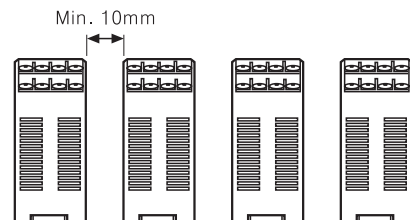
(Fig. 2) When it is NPN open collector

### Input signal line

- Please make the cable line short from input sensor to this controller.
- Do not put input signal line with other power cable in the same conduit.
- When need to extend the input signal line, please use shielded cable.

### Precaution for installation

When it is required to install more than two PA10, the space between two PA10 should be larger than 10mm in order for proper cooling.



### Other precautions

- Installation and dismantlement should be done with power off.
- Please check connections before wiring.
- Good ventilation must be considered to protect heating from inner components. (Ambient operating temperature is  $-10^{\circ}\text{C} \sim +50^{\circ}\text{C}$ )
- Do not supply over 100-240VAC.
- Do not install this controller at place where there are dust, steam, corrosive gas, water etc.
- AC power line must be separated from O.C output line or signal input line.
- This controller has been designed to have high speed response for O.C output. If use micro switch or limit switch for signal input, chattering might be occurred at O.C output.